

Dr. Dipankar Bhattacharya, Ph.D.

Marie Skłodowska-Curie Postdoctoral Fellow (2025–2027)
Dyson School, Imperial College London, United Kingdom

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Summary Statement

Knowledge as such does not have much power unless it is transformed into technology, which is capable of accelerating the progress of mankind. The long cherished dream of becoming the orchestrator of transformation leads my eyes and heart towards the academics and research.

Education

- 2016 – 2021 **Ph.D., Mechatronics Engineering** in Department of Mechanical and Mechatronics Engineering, The University of Auckland (UoA), 01/08/2016 – 14/04/2021.
Thesis title: *Robotic Soft Esophagus Design, Modelling, and Control for Endoprosthetic Stent Testing and Food Swallow Investigation*
- 2011 – 2013 **M.Tech, Systems and Control** in Department of Electrical Engineering, Indian Institute of Technology (IIT), 22/07/2011 – 04/07/2013.
Dissertation title: *Non-Linear Predictive Control Model using Relevance Vector Machine*. GPA: **8.4 / 10.0**
- 2004 – 2010 **B.Tech, Electronics and Communication Engineering**, North Eastern Regional Institute of Science and Technology (NERIST), 21/07/2004 – 23/06/2010.
Project title: *Design and Synthesis of a Sixth Order Tow Thomas Bi-quad filter*. GPA: **9.1 / 10.0**


Employment History

- 2025 – Current **Marie Skłodowska-Curie Postdoctoral Fellow** in the Dyson School of Engg, Imperial College London, Supervisor: Prof. Thrishantha Nanayakkara (Morph Lab), 01/11/2025 – Current.
CASREx: Cable-driven Arm Soft Re-configurable Exoskeleton for Muscle Impairment Rehabilitation
- 2025 **Senior Research Engineer–Control Systems** in the Center for Transformative Garment Production (TransGP), Supervisor: Prof. Kazuhiro Kosuge, 01/05/2025 – 31/10/2025.
Physics-based Cloth Manipulation with policy generated from imitation learning.
- Led a multidisciplinary team to develop high-performance models for fabric pre-sewing handling and folding.
 - Investigated feasibility and oversaw development and validation of robotic systems for fabric manipulation.
 - Translated industrial requirements into research deliverables; contributed to papers, reports, and grant proposals.
 - Mentoring and supervising 3 PhD students; reviewing and proofreading manuscripts.

Employment History (continued)

- 2024 – 2025
- **Postdoctoral Fellow** in the Center for Transformative Garment Production (TransGP), Supervisor: Prof. Kazuhiro Kosuge, 02/07/2024 – 30/04/2025.
 - **Visiting Research Associate** in the Department of Electrical and Electronic Engineering, Hong Kong University (HKU), 02/07/2024 – 31/10/2025.
- 2021 – 2024
- **Postdoctoral Fellow** in the Department of Mechanical and Automation, The Chinese University of Hong Kong. Supervisor: Prof. Darwin Lau, 01/03/2021 – 30/06/2024
Project title 1: Modeling and control of cable-driven robots with cable wrapping around obstacles and links.
Project title 2: Design of a cable-driven growing vine robot for safer false ceiling inspections.
Primary responsibilities:
 - Conduct independent and collaborative research, contributing to larger projects under PI supervision.
 - Write research articles, proposals, and technical reports.
 - Mentor undergraduate and postgraduate students; delivered lectures for **MAEG5090 Topics in Robotics** (Class strength: 50 students).
- 2021 – 2022
- **Visiting Postdoctoral Fellow** in Laboratoire des Sciences du Numérique de Nantes (LS2N), École Centrale de Nantes (ECN). Supervisors: Prof. Stephane Caro and Prof. Darwin Lau, 26/10/2021 – 05/01/2022.
Project title: Iterative-learning control of cable-driven parallel robot.
- 2017 – 2020
- **Graduate Teaching Assistant** at The University of Auckland.
Courses taken: MECHENG 706: Mechatronics Design Projects, MECHENG 306: Design of Sensing and Actuating Systems, ENGGEN 115: Principles of Engineering Design, ENGGEN 131: Introduction to Engineering Computation and Software Development.
 - Supervised undergraduate students on design projects, guiding problem-solving and ensuring practical solutions.
 - Delivered tutorials, workshops, and drop-in clinics; provided support via online forums (Piazza, CANVAS).
 - Managed laboratory sessions and coordinated TA activities, including safety briefings and student progress monitoring.
- 2018 – 2019
- **Research Assistant** at The University of Auckland, under the direction of Prof Peter Xu, 09/01/2018 – 08/01/2019.

Employment History (continued)

2013–2016  **Lecturer (Assistant Professor Grade-1)** in School of Electrical, Electronics and Communication Engineering (SEECE) at Galgotia's University (GU), 19/07/2013–18/06/2016.

- Delivering lectures for undergraduate and postgraduate courses including Control System, Process Control, and Linear Integrated Circuit.
- Developing and constructing teaching materials for lectures.
- Supporting students in a pastoral/advisory role.
- Delivering laboratory sessions, and managing and supervising staffs and lab technicians.
- Supervision of final year undergraduate projects.

Research Publications

Journal (Published/Accepted)

- 1 Jin*, B., Kobayashi*, A., Bhattacharya, D., Seino, A., Tokuda, F., Tien, N., & Kosuge, K. (2025). Automated Straight-line Sewing of Stretchable Fabrics with Different Lengths [*Equal contribution.]. *IEEE Robotics and Automation Letters*, 1–8. <https://doi.org/10.1109/LRA.2025.3619791>
- 2 Bhattacharya, D., Cheung, T. K., Wang, Y., & Lau, D. (2025). Kinematic and Dynamic Modeling of Cable-Object Interference and Wrapping in Complex Geometrical-Shaped Cable-Driven Parallel Robots. *Mechanism and Machine Theory*, 214, 106092. <https://doi.org/10.1016/j.mechmachtheory.2025.106092>
- 3 Bhattacharya, D., Chan, Y. P., Shang, S., Chan, Y. S., Tan, Y., & Lau, D. (2023). Tri-Space Operational Control of Redundant Multilink and Hybrid Cable-Driven Parallel Robots Using an Iterative-Learning based Reactive Approach. *IEEE Transactions on Control Systems and Technology*. <https://doi.org/10.1109/TCST.2023.3263689>
- 4 Bhattacharya, D., Cheng, L. K., & Xu, W. (2021). Nonlinear Model Predictive Control of a Robotic Soft Esophagus for Endoprosthetic Stent Testing. *IEEE Transactions on Industrial Electronics*. <https://doi.org/doi:10.1109/TIE.2021.3121755>
- 5 Bhattacharya, D., Jesna, S., Cheng, L. K., & Xu, W. (2021). RoSE: A Robotic Soft Esophagus for Endoprosthetic Stent Testing. *Soft Robotics*. <https://doi.org/10.1089/soro.2019.0205>
- 6 Dang, Y., Liu, Y., Hashem, R., Bhattacharya, D., Allen, J., Stommel, M., Cheng, L. K., & Xu, W. (2021). SoGut: A Soft Robotic Gastric Simulator. *Soft Robotics*. <https://doi.org/10.1089/soro.2019.0136>
- 7 Bhattacharya, D., Cheng, L. K., & Xu, W. (2020). Sparse Machine Learning Discovery of Dynamic Differential Equation of an Esophageal Swallowing Robot. *IEEE Transactions on Industrial Electronics*, 67(6), 4711–4720. <https://doi.org/10.1109/TIE.2019.2928239>
- 8 Bhattacharya, D., Nisha, M. G., & Pillai, G. (2015). Relevance vector-machine-based solar cell model. *International Journal of Sustainable Energy*, 34(10), 685–692. <https://doi.org/10.1080/14786451.2014.885030>
- 9 Dong, W., Bhattacharya, D., Kobayashi, A., Seino, A., Tokuda, F., Huang, X., Tang, K., Tien, N. C., & Kosuge, K. (2025). Precise Top-layer Fabric Segmentation for Fabric Destacking with Edge- and Shape-Aware Deep Networks. *2025 IEEE International Conference on Mechatronics and Automation (ICMA)*, 1343–1348.
- 10 Bhattacharya, D., Cheng, L. K., & Xu, W. (2018). Testing and Analysis of Migration Displacement of a Flared Stent Deployed in an Esophageal Swallowing Robot. *25th International Conference on Mechatronics and Machine Vision in Practice (M2VIP)*, 1–6. <https://doi.org/10.1109/M2VIP.2018.8600911>

- 11 Bhattacharya, D., Cheng, L. K., Dirven, S., & Xu, W. (2017). Actuation planning and modeling of a soft swallowing robot. *24th International Conference on Mechatronics and Machine Vision in Practice (M2VIP)*, 1–6.
<https://doi.org/10.1109/M2VIP.2017.8211476>

Books and Chapters






- 1 Bhattacharya, D., Cheng, L. K., Dirven, S., & Xu, W. (2019). *Artificial intelligence approach to the trajectory generation and dynamics of a soft robotic swallowing simulator*. Springer International Publishing.
https://doi.org/10.1007/978-3-319-78452-6_1

In Review/Preparation




- 1 Bhattacharya*, D., Tang*, K., Hang, X., Tokuda, F., Tien, N., & Kosuge, K. (2026). RTFF: Random-to-Target Fabric Flattening Policy Using Dual-Arm Manipulator, IEEE International Conference on Robotics and Automation (ICRA) [in review. *Equal contribution].
- 2 Wang, W., Bhattacharya, D., Kobayashi, A., Seino, A., Tokuda, F., Tien, N., & Kosuge, K. (n.d.). Automated Fabric Alignment Using Global-Local Optimization and Point Cloud Registration, IEEE Transactions on Automation Science and Engineering (T-ASE) [in review].
- 3 Cheung, T., Bhattacharya, D., & Lau, D. (n.d.). Rapidly Deployable Deformable Frame Cable-Driven Parallel Robots with Small Footprint [in preparation].
- 4 Wang, Y., Bhattacharya, D., & Lau, D. (n.d.). Static modelling and workspace analysis with arbitrary cable attachment design in a cable-driven parallel robot with passive backbone, IEEE Transactions on Automation Science and Engineering [in preparation].

Grants and Scholarships

Grants/Fellowships



- 2025  Recipient, **Horizon Europe Marie Skłodowska-Curie Postdoctoral Fellowship** for the project "CASREx" (Grant No. 101205678), hosted at **Imperial College London**. Funded under HORIZON-MSCA-2024-PF-01-01. Duration: 24 months, **EUR 276,187.92**.
- 2023  Co-authored Innovation and Technology Fund (ITF), Partnership Research Program (PRP) grant.
- 2022  Co-authored Research Talent Hub for ITF project (RTH-ITF) grant.
- 2018  Recipient, Dynamic testing of implant stents using Robotic Soft Esophagus (RoSE), BvW Holding, Cham, Switzerland (39,000 NZD, 1 year).
- 2018, 2019  Recipient, Riddet Travel grant, Riddet Institute Centre of Research Excellence (3,000 NZD).

Scholarships

- 2019–2020  Recipient, Doctor of Philosophy Scholarship, University of Auckland.
- 2016–2019  Recipient, Doctor of Philosophy Scholarship, Riddet Institute Centre of Research Excellence.
- 2011–2013  Recipient, Masters of technology Scholarship, Ministry of Human Resource (MHRD) GATE scholarship.

Academic Awards, and Miscellaneous Achievements

Academic Awards

- 15/12/25  Selected, **European Talent Academy 2026** (Imperial College London, TU Munich, Politecnico di Milano).
- 2017  Recipient, **Best Conference paper award**, 5th International Conference on Robotic Intelligence Technology and Applications (RiTA), Daejeon, Korea.

Academic Awards, and Miscellaneous Achievements (continued)

- Ranked **2nd** in poster presentation in Delivery of Functionality in Complex Food Systems (DoF 2017) Conference.

Competitive Examinations

- 2011 **Percentile: 99.12% (Rank 1,211/1,37,853)** in Graduate Aptitude Test of Engineering (GATE).
- 2010 **Percentile: 96.00%** in Graduate Aptitude Test of Engineering (GATE).
- 2004 **Ranked 31st** in All India Junior mathematics Olympiad.

Professional Activities

- 05/02/26 **Invited Speaker, Dyson Engineering Departmental Seminar**, Imperial College London.
- 29/01/26 **Invited Speaker, Imperial Robotics Postgrad Committee**, Imperial College London. Talk: *Learning-based Fabric Manipulation with Mesh Perception and Visual Servoing*.
- 28/01/26 **Delivered lecture on Robotics Simulation and Control using PyDrake** for DESE71002 Robotics Research Projects, Dyson School of Engineering, Imperial College London.
- 08/08/25 **Invited Speaker, World Robotics Conference (WRC 2025)**, Beijing, China. Talk: *Fabric modeling and perception for garment manufacturing*.
- 03/08/25 **Workshop Organizer and Presenter, IEEE ICMA 2025**, Beijing, China. Talk: *Mesh-based Fabric State Estimation and Manipulation*.
- 29/05/23 **Poster Presentation, IEEE ICRA 2023**, ExCeL London, United Kingdom.
- 2018 **Presenter, BioMouth 2018 Meet**, Auckland, New Zealand.
- 2021 - Current **Reviewer of IEEE Robotics and Automation Letters (RAL), IEEE International Conference on Robotics and Automation (ICRA), ASME Journal of Mechanisms and Robotics (JMR).**
- 2017 - Current **Member of the Institute of Electrical and Electronics Engineers (IEEE).**
- 2014 **Former member of the Electrical Engineering Society (EES), IIT Roorkee, and NERIST Electronics Society (NES), NERIST.**
- 2006 **Have an 'Outstanding Certificate' in National Service Scheme (NSS) for contributing in activities like blood donation camps, village cleanliness programmes and children education.**

Skills

- Languages **Strong reading, writing and speaking competencies for English, and Hindi.**
- Coding **PyTorch, Gym framework, Blender, MATLAB, Python, ROS, LabVIEW, Assembly level languages (Microprocessor: 8085, 8086 and MASM 32 and Microcontroller: 8051), and L^AT_EX.**
- Software and misc **Blender, SOLIDWORKS, Inventor, Inkscape, Git, and Lightroom.**
- Microprocessors **Raspberry Pi, myRIO, and Arduino.**

References

Prof Kazuhiro Kosuge

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